

Linear Algebra Common Topics List¹

1. Computations and Proofs

- (a) The course should include both computations and proofs

2. Geometry and Algebra of Vectors

- (a) Vector addition and scalar multiplication
- (b) Linear combinations

3. Systems of Linear Equations

- (a) Linear versus nonlinear equations
- (b) Homogeneous versus nonhomogeneous systems
- (c) Coefficient matrix and augmented matrix
- (d) Row echelon form and reduced row echelon form
- (e) Gaussian elimination
- (f) Elementary row operations
- (g) Superposition of linear systems: Relationship between the solutions sets of associated homogeneous and nonhomogeneous systems

4. Matrices

- (a) Matrix addition and multiplication
- (b) Properties of matrix multiplication
- (c) Transposes and symmetric matrices
- (d) Matrix Inverses and Invertibility
- (e) Determinant
 - Computing determinants
 - Effect of elementary row operations
 - Relationship to invertibility
- (f) Trace

5. Vector Spaces

- (a) Definition of a vector space
- (b) Examples including \mathbb{R}^n and function spaces
- (c) Subspaces, including lines and planes through the origin as examples

6. Bases

- (a) Span of a set of vectors

¹This list was approved by the department on 5/3/19.

- (b) Linear dependence and independence
- (c) Basis for a vector space
- (d) Dimension of a vector space

7. Linear Transformations

- (a) Definition of a linear transformation
- (b) Relationship between matrices and linear transformations
- (c) Row space, column space, and null space of a matrix
- (d) Rank and nullity of a matrix; rank-nullity theorem
- (e) Image and kernel of a linear transformation
- (f) The column space of a matrix is the image of the transformation

8. Eigenvectors and Eigenvalues

- (a) Formal definitions of eigenvectors and eigenvalues
- (b) Characteristic polynomial and characteristic equation
- (c) Properties of eigenvectors, including relationships to the transpose and inverse
- (d) The determinant is the product of the eigenvalues

9. Similarity and Diagonalization

- (a) Similarity invariants, like eigenvalues, determinant, and trace
- (b) Definition of diagonalizable matrix
- (c) If a matrix has distinct eigenvalues it is diagonalizable

10. Dot Products and Inner Products

- (a) Definitions
- (b) Vector norms and angles
- (c) Orthogonal Vectors

11. Projection

- (a) Projection onto a vector
- (b) Projection onto a subspace
- (c) Orthogonal complement of a subspace
- (d) Orthogonal decomposition of a vector
- (e) The nullspace and row space of a matrix are orthogonal complements

12. Orthogonal bases

- (a) An orthogonal set is linearly independent
- (b) Orthonormal basis

Examples of Additional Topics

- Complex vector spaces
- Gram-Schmidt process
- Orthogonal Matrices
- LU factorization
- QR factorization
- Markov Chains
- Principal Component Analysis
- Least Squares Approximation
- Distance between points, lines, and planes
- Matrix Block Multiplication
- Cramer's Rule
- Iterative Methods
- Singular Value Decomposition
- Cayley-Hamilton Theorem
- Jordan Canonical Form and Rational Canonical Form
- Linear Differential Equations as the kernel of a linear transformation